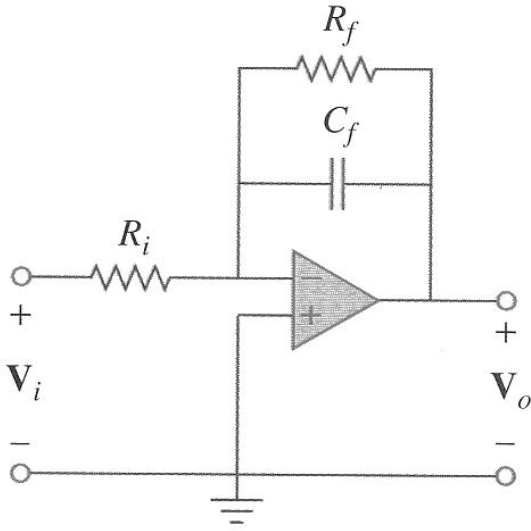


# ELG3336: Op Amp-based Active Filters

- **Advantages:**
  - Reduced size and weight, and therefore parasitics.
  - Increased reliability and improved performance.
  - Simpler design than for passive filters and can realize a wider range of functions as well as providing voltage gain.
  - In large quantities, the cost of an IC is less than its passive counterpart.
- **Disadvantages:**
  - Limited bandwidth of active devices limits the highest attainable pole frequency and therefore applications above 100 kHz (passive RLC filters can be used up to 500 MHz).
  - The achievable quality factor is also limited.
  - Require power supplies (unlike passive filters).
  - Increased sensitivity to variations in circuit parameters caused by environmental changes compared to passive filters.
- For applications, particularly in voice and data communications, the economic and performance advantages of active RC filters far outweigh their disadvantages.

# First-Order Low-Pass Filter



$$H(f) = \frac{V_o}{V_i} = -\frac{Z_f}{Z_i}$$

$$\frac{1}{Z_f} = \frac{1}{R_f} + \frac{1}{\frac{1}{j2\pi f C_f}} = \frac{1}{R_f} + \frac{j2\pi f R_f C_f}{R_f}$$

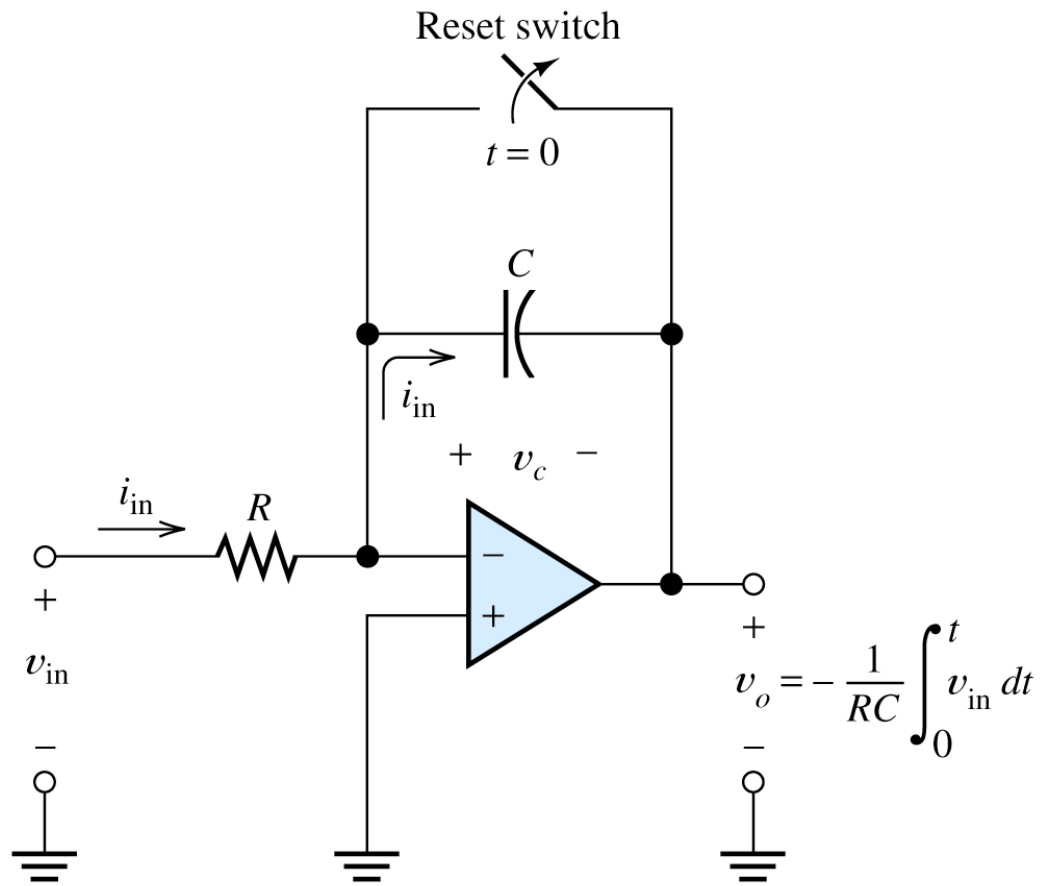
$$Z_f = \frac{R_f}{1 + j2\pi f R_f C_f}$$

$$H(f) = -\frac{Z_f}{Z_i} = -\left(\frac{R_f}{R_i}\right) \frac{1}{1 + j2\pi f R_f C_f}$$

$$= -\left(\frac{R_f}{R_i}\right) \left[ \frac{1}{1 + j(f / f_B)} \right]$$

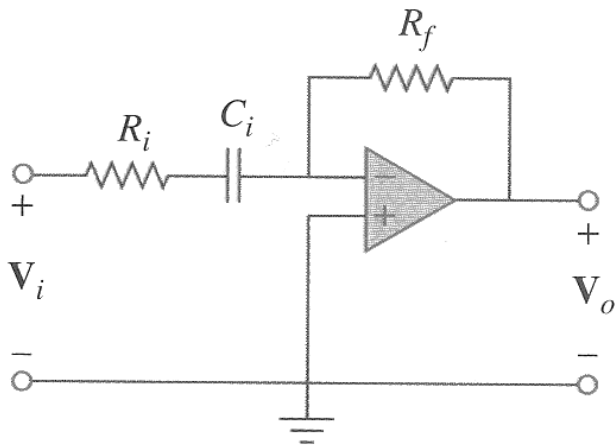
$$f_B = \frac{1}{2\pi R_f C_f}$$

A low-pass filter with a dc gain of  $-R_f/R_i$



$$v_o(t) = -\frac{1}{RC} \int_0^t v_{in}(t) dt$$

# First-Order High-Pass Filter



$$H(f) = \frac{v_o}{v_i} = -\frac{Z_f}{Z_i}$$

$$Z_i = R_i + \frac{1}{j2\pi f C_i} \quad Z_f = R_f$$

$$H(f) = -\frac{Z_f}{Z_i} = -\frac{R_f}{R_i + \frac{1}{j2\pi f C_i}}$$

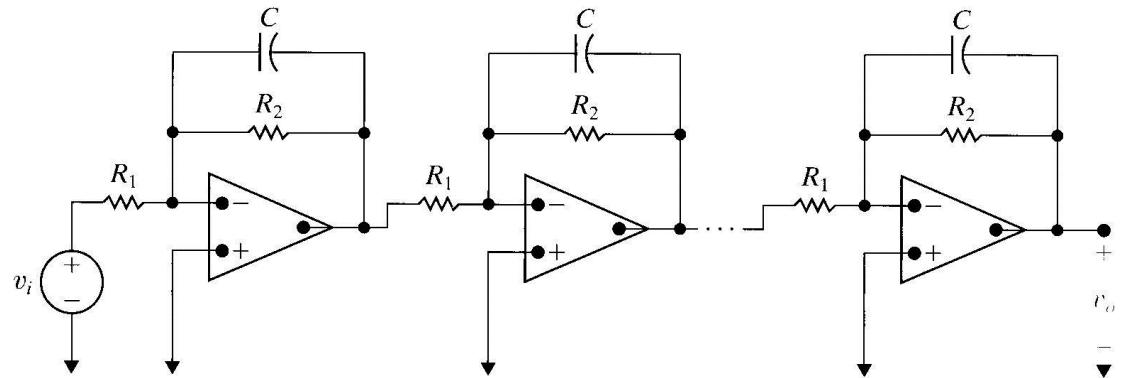
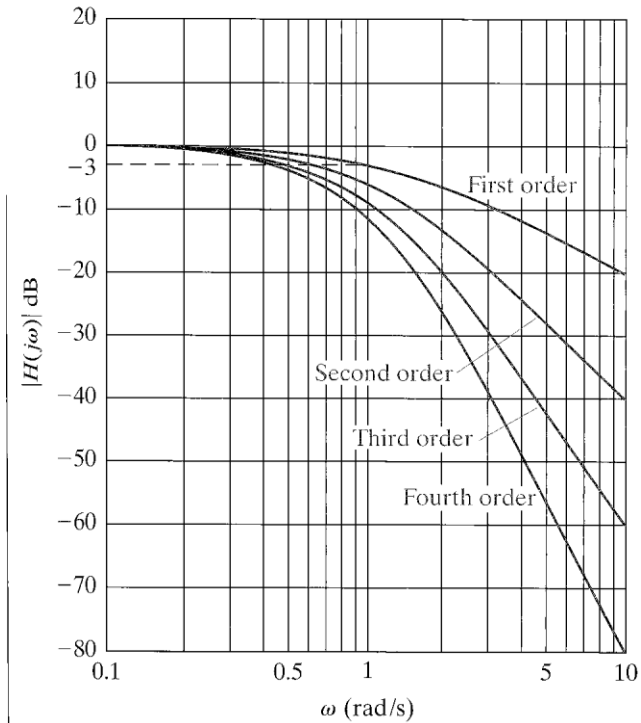
$$= -\frac{j2\pi f R_f C_i}{1 + j2\pi f R_i C_i} = -\left(\frac{R_f}{R_i}\right) \frac{j2\pi f R_f C_i}{1 + j2\pi f R_i C_i}$$

$$= -\left(\frac{R_f}{R_i}\right) \left[ \frac{j(f / f_B)}{1 + j(f / f_B)} \right]$$

$$f_B = \frac{1}{2\pi R_i C_i}$$

A high-pass filter with a high frequency gain of  $-R_f/R_i$

# Higher Order Filters

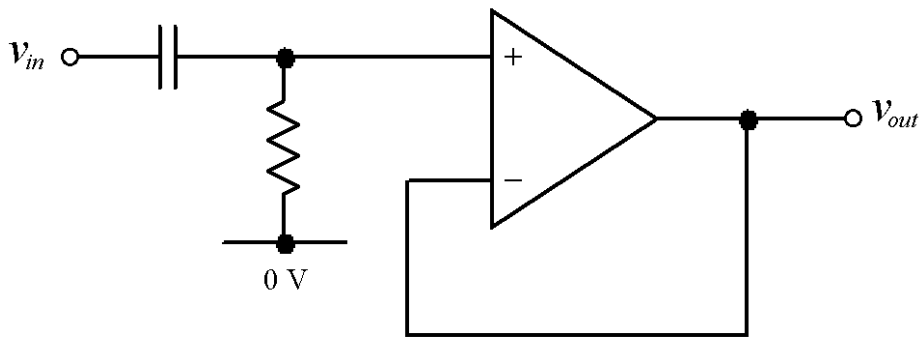


$$H(f) = H_1(f)H_2(f) \dots H_n(f)$$

$$= (-1)^n \left( \frac{R_f}{R_i} \right)^n \left[ \frac{1}{1 + j(f / f_B)} \right]^n$$

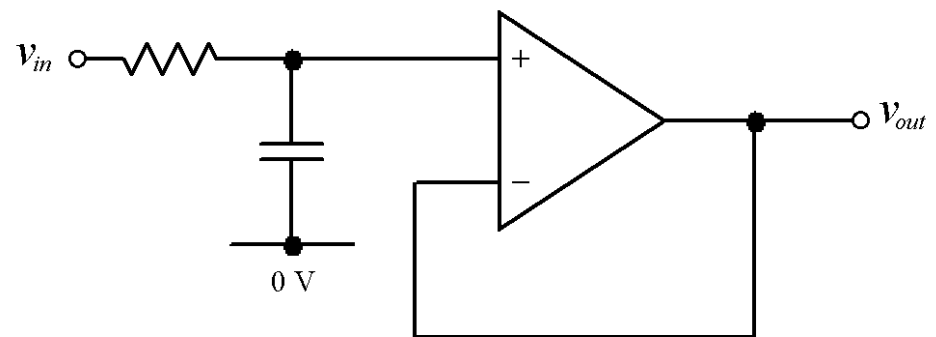
# Single-Pole Active Filter Designs

## High Pass



$$\begin{aligned}\frac{v_{out}}{v_{in}} &= \frac{1}{\frac{1}{sCR} + 1} = \frac{1}{\frac{1+sRC}{sCR}} \\ &= \frac{sRC}{RC(s+1/RC)} = \frac{s}{(s+1/RC)}\end{aligned}$$

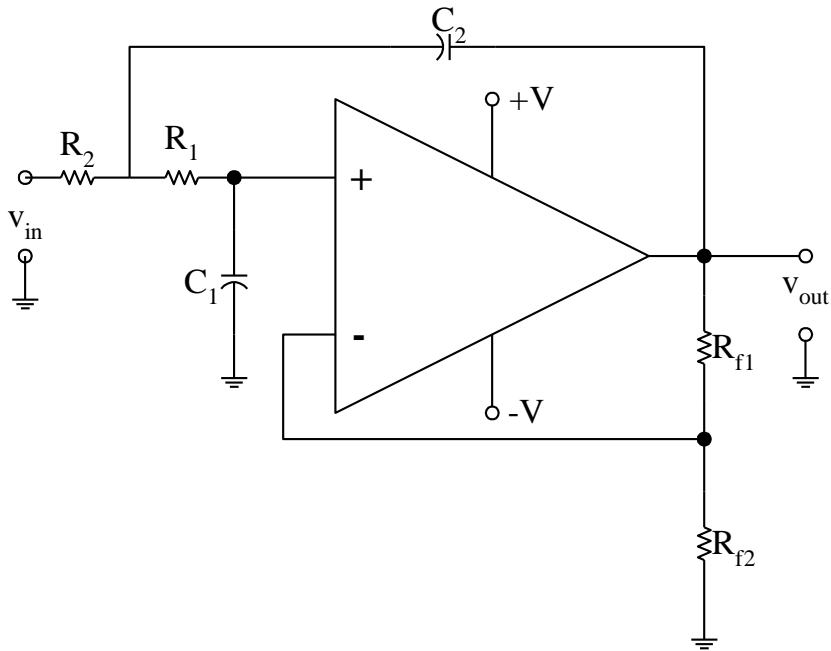
## Low Pass



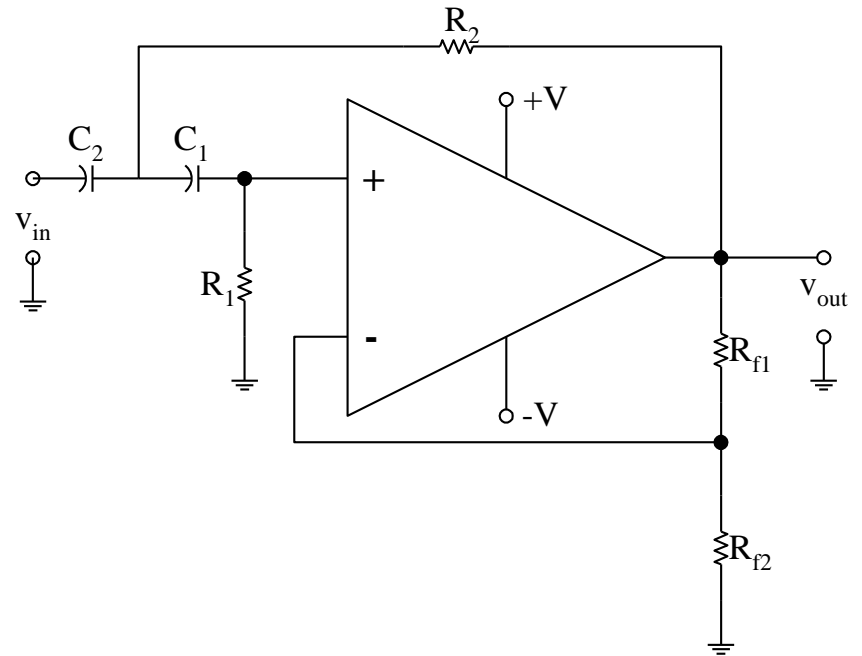
$$\frac{v_{out}}{v_{in}} = \frac{1/RC}{s+1/RC}$$

# Two-Pole (Sallen-Key) Filters

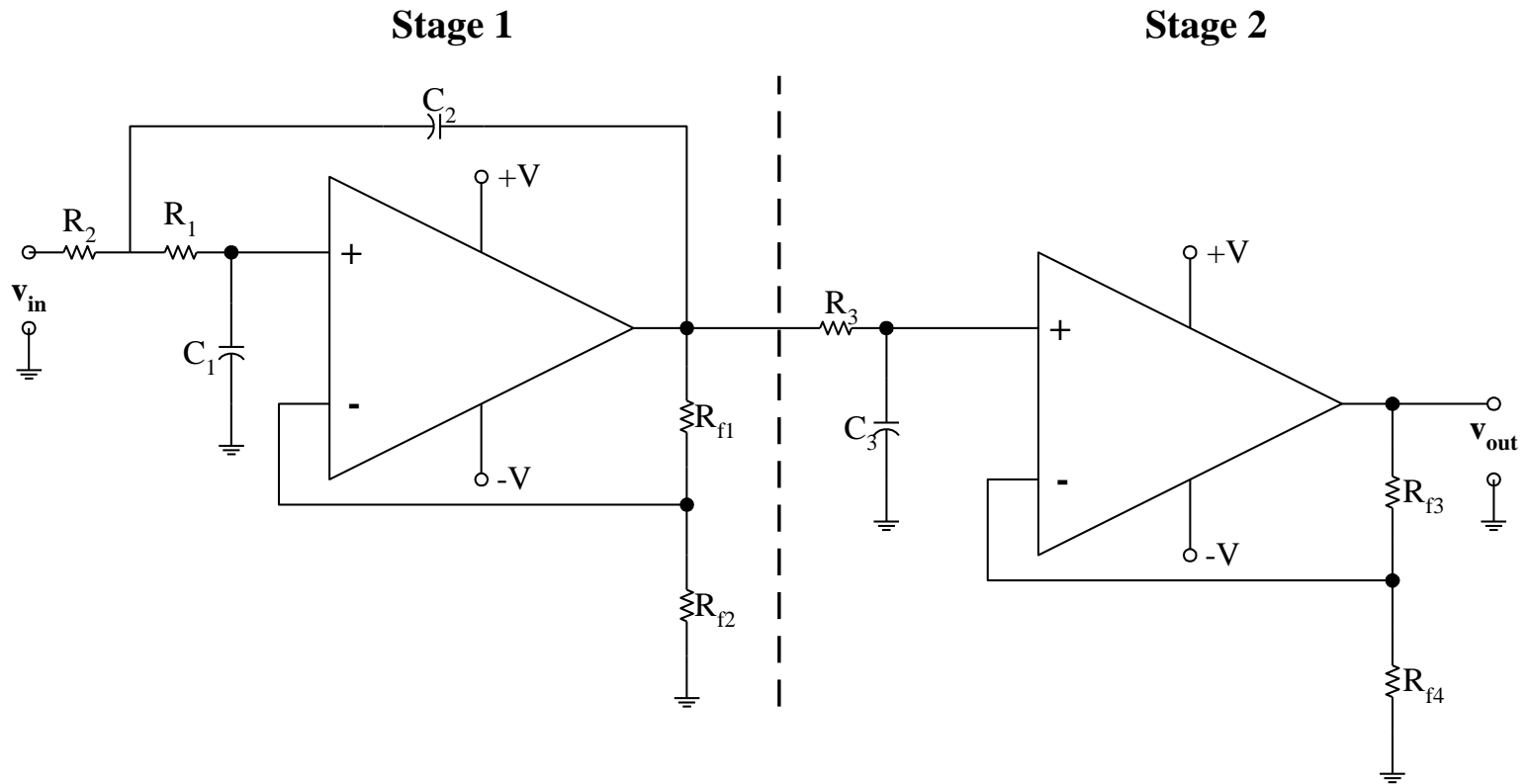
Low Pass Filter



High Pass Filter

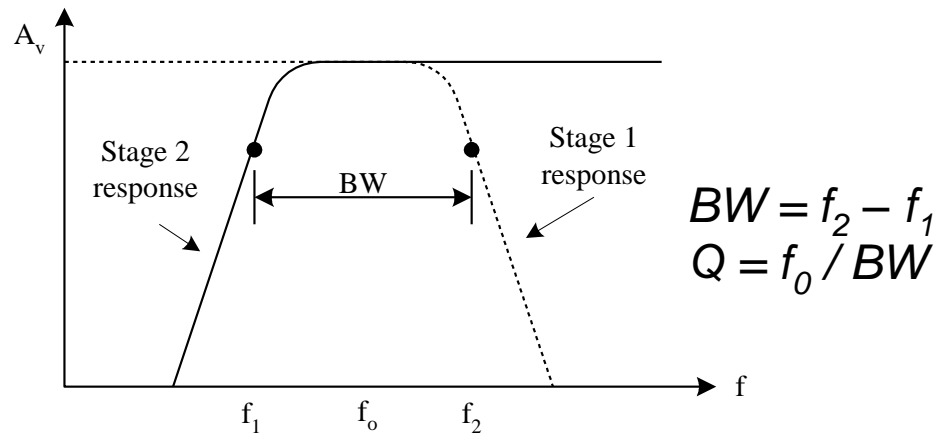
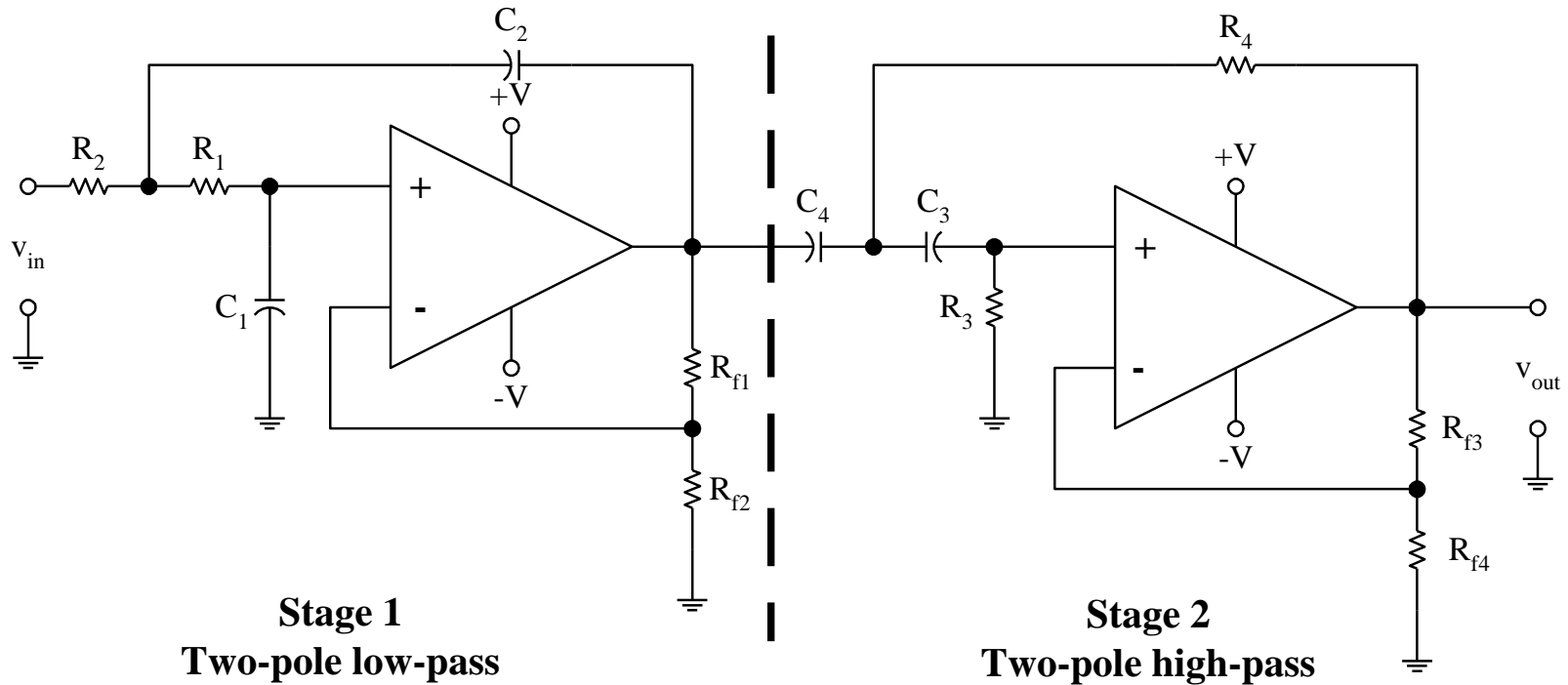


# Three-Pole Low-Pass Filter

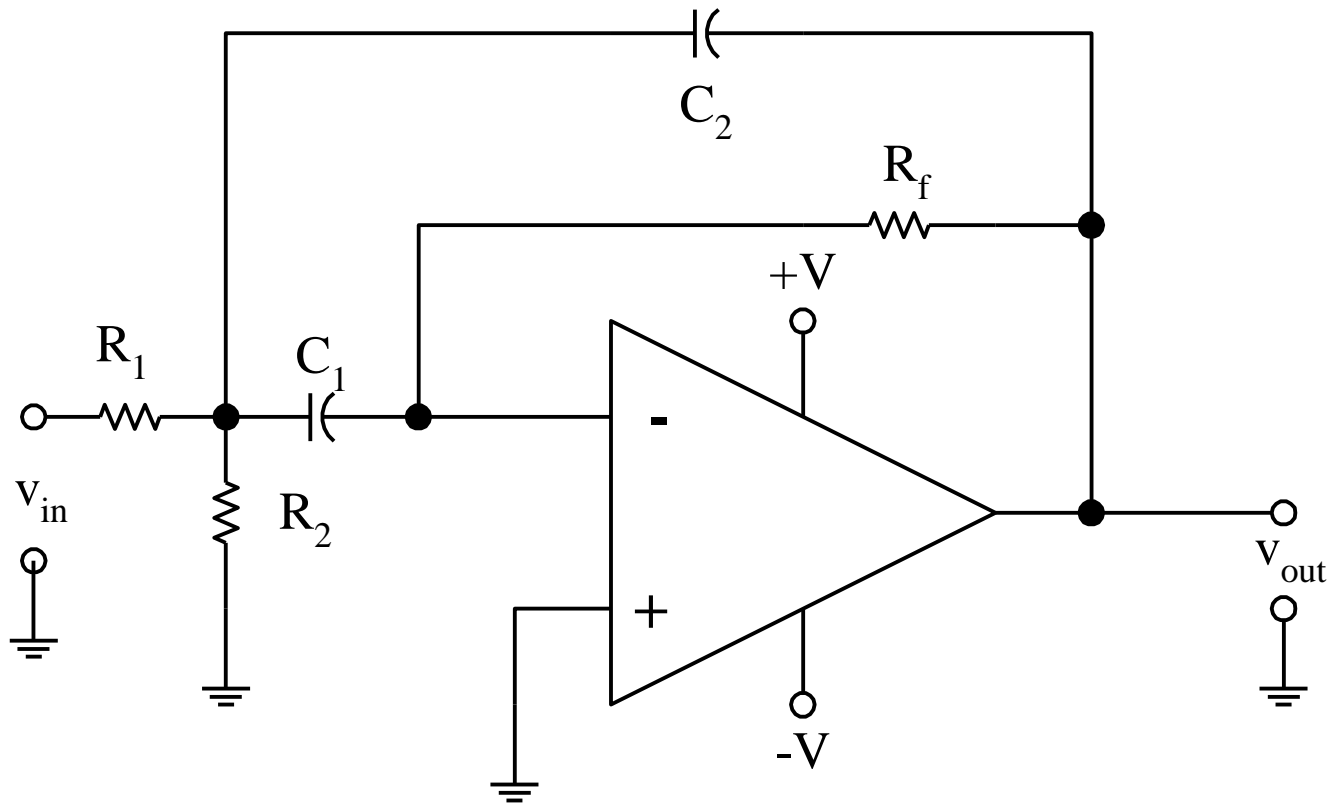




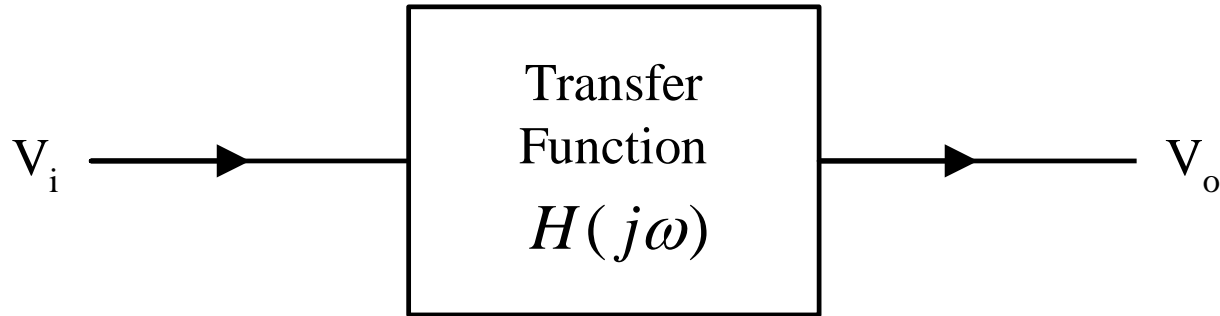
# Two-Stage Band-Pass Filter



# Multiple-Feedback Band-Pass Filter



# Transfer function $H(j\omega)$



$$H(j\omega) = \frac{V_o(j\omega)}{V_i(j\omega)}$$

$$|H| = \sqrt{\text{Re}(H)^2 + \text{Im}(H)^2}$$

$$H = \text{Re}(H) + j \text{Im}(H)$$

$$\angle H = \tan^{-1} \left( \frac{\text{Im}(H)}{\text{Re}(H)} \right) \quad \text{Re}(H) > 0$$

$$\angle H = 180^\circ + \tan^{-1} \left( \frac{\text{Im}(H)}{\text{Re}(H)} \right) \quad \text{Re}(H) < 0$$

# Corner Frequency

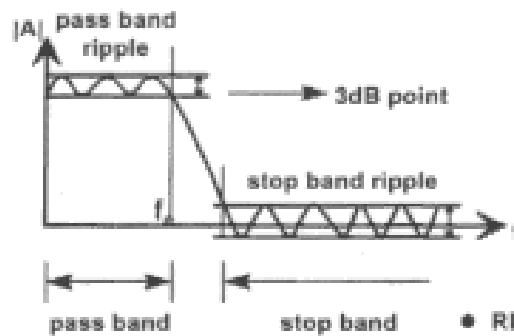
- The significance of the break frequency is that it represents the frequency where

$$A_v(f) = 0.707 \angle -45^\circ$$

- This is where the output of the transfer function has an amplitude *3-dB* below the input amplitude, and the output phase is shifted by  $-45^\circ$  relative to the input.
- Therefore,  $f_c$  is also known as the **3-dB frequency** or the **corner frequency**.

# PERFORMANCE CRITERIA

## AMPLITUDE RESPONSE



$$20 \log_{10} |A| = \text{Gain in dB}$$

$$f_c = \text{Cut-off Frequency}$$

$$\text{Gain at 3dB point (at } f_c) = \frac{|A|}{\sqrt{2}}$$

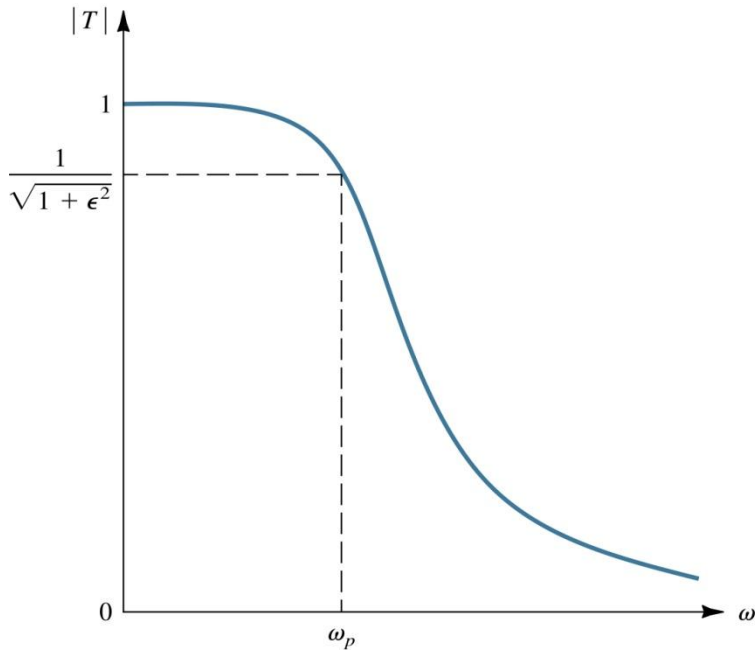
- RIPPLE IN PASS BAND CAUSES NON-LINEARITY
- POSSIBLE TO DESIGN WITH NO RIPPLE
- RIPPLE IN STOP BAND IS LESS IMPORTANT
- FALL OFF dB / Decade (Gain in dB / Decade of  $f$ )
- STOP BAND ATTENUATES (SAY - 40dB)

Bode plots use a logarithmic scale for frequency, where a *decade* is defined as a range of frequencies where the highest and lowest frequencies differ by a factor of 10.

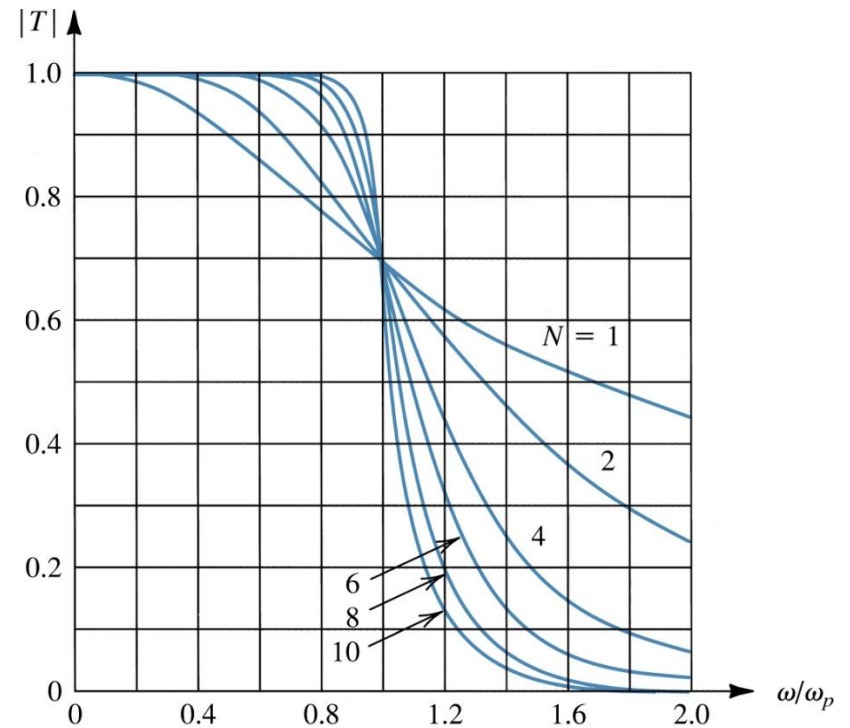
# Real Filters

- Butterworth Filters
  - Flat Pass-band.
  - $20n$  dB per decade roll-off.
- Chebyshev Filters
  - Pass-band ripple.
  - Sharper cut-off than Butterworth.
- Elliptic Filters
  - Pass-band and stop-band ripple.
  - Even sharper cut-off.
- Bessel Filters
  - Linear phase response – i.e. no signal distortion in pass-band.

# Butterworth Filters

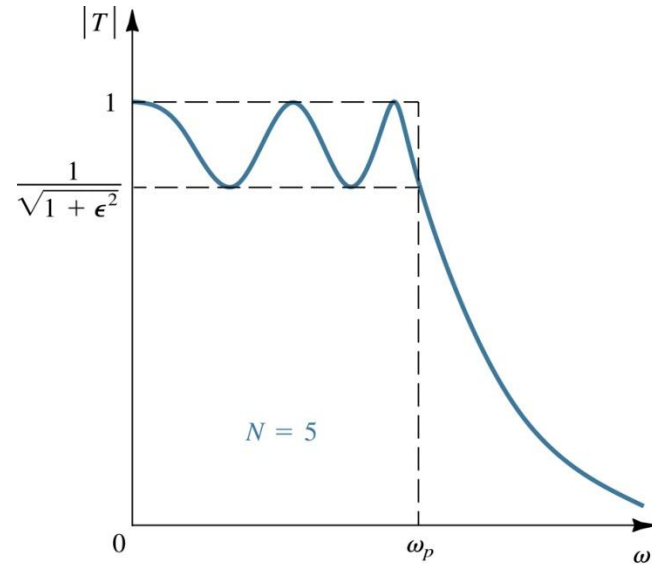
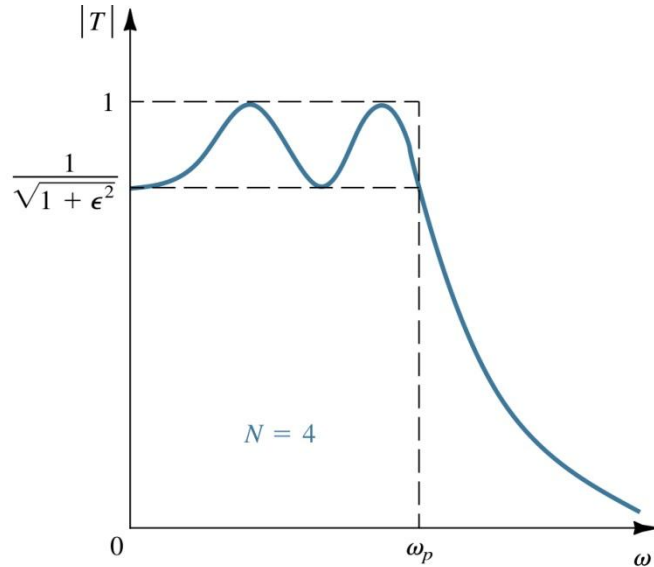


The magnitude response of a Butterworth filter.



Magnitude response for Butterworth filters of various order with  $\epsilon = 1$ . Note that as the order increases, the response approaches the ideal brickwall type transmission.

# Chebyshev Filters



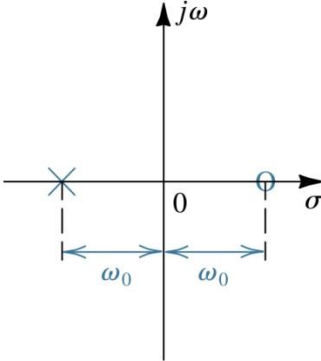
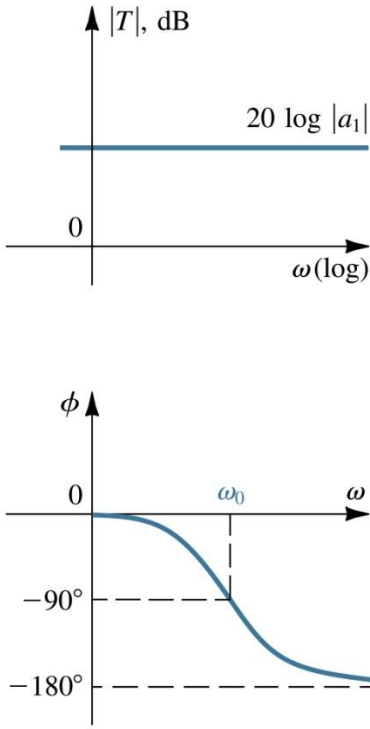
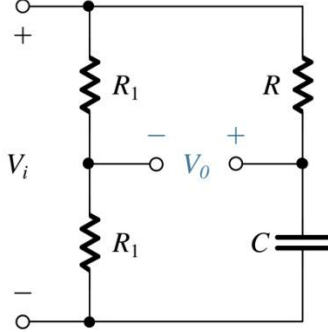
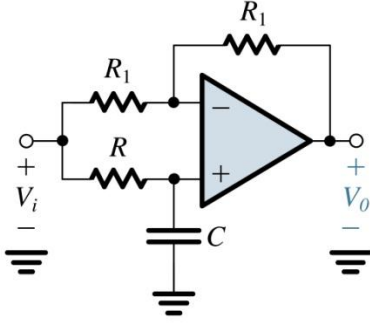
Sketches of the transmission characteristics of a representative even- and odd-order Chebyshev filters.



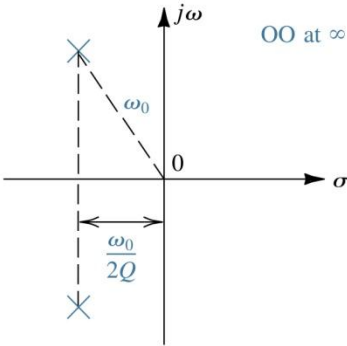
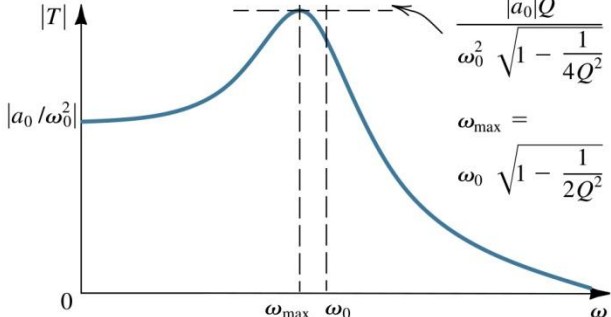
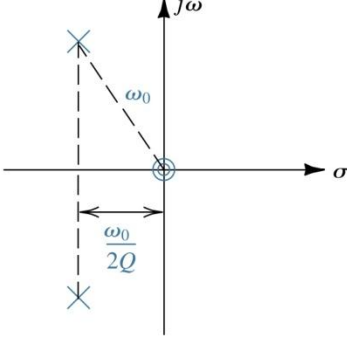
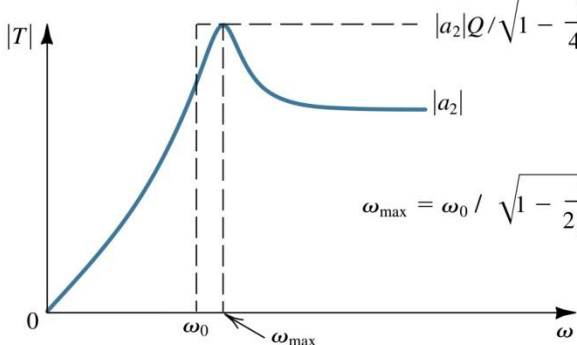
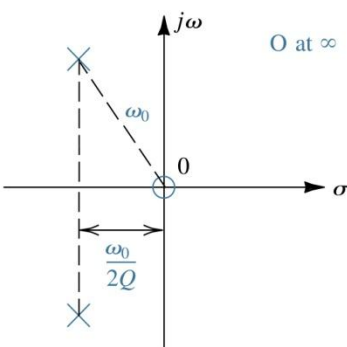
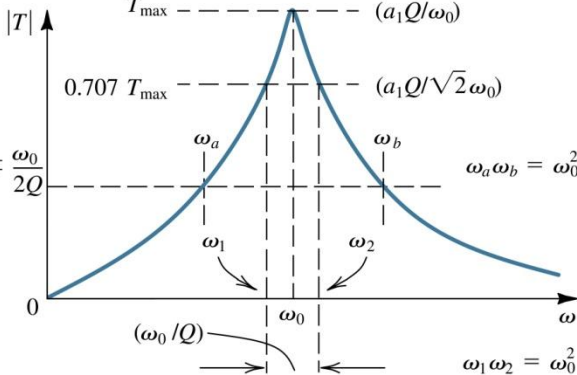
# First-Order Filter Functions

Filter Type and $T(s)$	$s$ -Plane Singularities	Bode Plot for $ T $	Passive Realization	Op Amp-RC Realization
<p>(a) Low-Pass (LP)</p> $T(s) = \frac{a_0}{s + \omega_0}$			<p> <math>CR = \frac{1}{\omega_0}</math>                      dc gain = 1                 </p>	<p> <math>CR_2 = \frac{1}{\omega_0}</math>                      dc gain = <math>-\frac{R_2}{R_1}</math> </p>
<p>(b) High-Pass (HP)</p> $T(s) = \frac{a_1 s}{s + \omega_0}$			<p> <math>CR = \frac{1}{\omega_0}</math>                      High-frequency gain = 1                 </p>	<p> <math>CR_1 = \frac{1}{\omega_0}</math>                      High-frequency gain = <math>-\frac{R_2}{R_1}</math> </p>
<p>(c) General</p> $T(s) = \frac{a_1 s + a_0}{s + \omega_0}$			<p> <math>(C_1 + C_2)(R_1 // R_2) = \frac{1}{\omega_0}</math>  <math>C_1 R_1 = \frac{a_0}{a_1}</math>                      dc gain = <math>\frac{R_2}{R_1 + R_2}</math>                      HF gain = <math>\frac{C_1}{C_1 + C_2}</math> </p>	<p> <math>C_2 R_2 = \frac{1}{\omega_0}</math>  <math>C_1 R_1 = \frac{a_1}{a_0}</math>                      dc gain = <math>-\frac{R_2}{R_1}</math>                      HF gain = <math>-\frac{C_1}{C_2}</math> </p>

# First-Order Filter Functions

$T(s)$	Singularities	$ T $ and $\phi$	Passive Realization	Op Amp-RC Realization
$T(s) = -a_1 \frac{s - \omega_0}{s + \omega_0}$ $a_1 > 0$			 <p style="text-align: center;"> <math>CR = 1/\omega_0</math>            Flat gain (<math>a_1</math>) = 0.5         </p>	 <p style="text-align: center;"> <math>CR = 1/\omega_0</math>            Flat gain (<math>a_1</math>) = 1         </p>

# Second-Order Filter Functions

Filter Type and $T(s)$	$s$ -Plane Singularities	$ T $
<p>(a) Low-Pass (LP)</p> $T(s) = \frac{a_0}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$ <p>dc gain = <math>\frac{a_0}{\omega_0^2}</math></p>	 <p><math>\infty</math> at <math>\infty</math></p>	 $\frac{ a_0 Q}{\omega_0^2 \sqrt{1 - \frac{1}{4Q^2}}}$ $\omega_{\max} = \omega_0 \sqrt{1 - \frac{1}{2Q^2}}$
<p>(b) High-Pass (HP)</p> $T(s) = \frac{a_2 s^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$ <p>High-frequency gain = <math>a_2</math></p>		 $ a_2 Q / \sqrt{1 - \frac{1}{4Q^2}}$ $\omega_{\max} = \omega_0 / \sqrt{1 - \frac{1}{2Q^2}}$
<p>(c) Bandpass (BP)</p> $T(s) = \frac{a_1 s}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$ <p>Center-frequency gain = <math>\frac{a_1 Q}{\omega_0}</math></p>	 <p><math>\infty</math> at <math>\infty</math></p>	 $\omega_1, \omega_2 = \omega_0 \sqrt{1 + \frac{1}{4Q^2}} \mp \frac{\omega_0}{2Q}$ $\omega_a \omega_b = \omega_0^2$ $\omega_1 \omega_2 = \omega_0^2$

# Second-Order Filter Functions

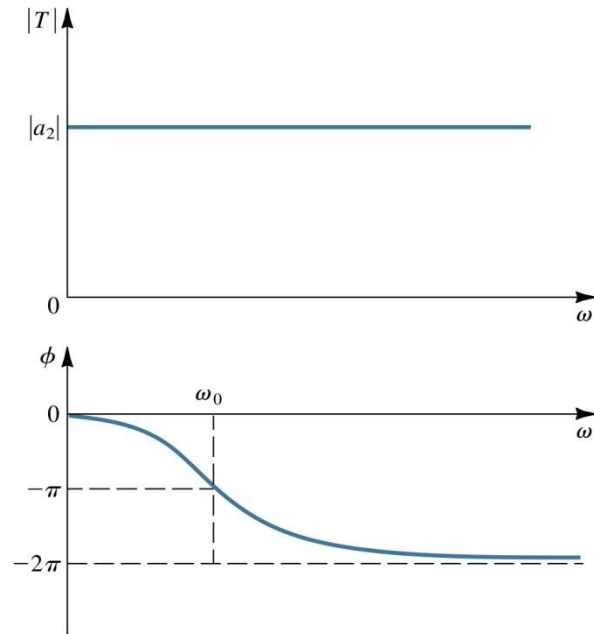
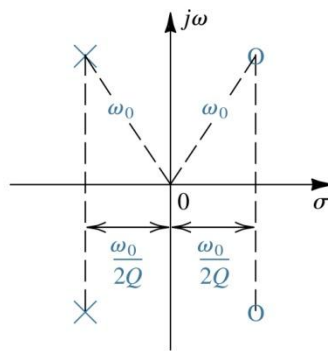
<p>(d) Notch</p> $T(s) = a_2 \frac{s^2 + \omega_0^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$ <p>dc gain = high-frequency gain = <math>a_2</math></p>		<p><math>\omega_1 \omega_2 = \omega_0^2</math></p>
<p>(e) Low-Pass Notch (LPN)</p> $T(s) = a_2 \frac{s^2 + \omega_n^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$ <p><math>\omega_n \geq \omega_0</math> dc gain = <math>a_2 \frac{\omega_n^2}{\omega_0^2}</math> high-frequency gain = <math>a_2</math></p>		$\omega_{\max} = \omega_0 \sqrt{\frac{\left(\frac{\omega_n^2}{\omega_0^2}\right)\left(1 - \frac{1}{2Q^2}\right) - 1}{\frac{\omega_n^2}{\omega_0^2} + \frac{1}{2Q^2} - 1}}$
<p>(f) High-Pass Notch (HPN)</p> $T(s) = a_2 \frac{s^2 + \omega_n^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$ <p><math>\omega_n \leq \omega_0</math> dc gain = <math>a_2 \frac{\omega_n^2}{\omega_0^2}</math> high-frequency gain = <math>a_2</math></p>		$T_{\max} = \frac{ a_2  \frac{ \omega_n^2 - \omega_{\max}^2 }{\sqrt{(\omega_0^2 - \omega_{\max}^2)^2 + \left(\frac{\omega_0}{Q}\right)^2 \omega_{\max}^2}}}{ a_2 }$

# Second-Order Filter Functions

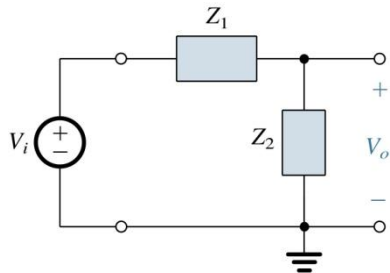
(g) All-Pass  
(AP)

$$T(s) = a_2 \frac{s^2 - s \frac{\omega_0}{Q} + \omega_0^2}{s^2 + s \frac{\omega_0}{Q} + \omega_0^2}$$

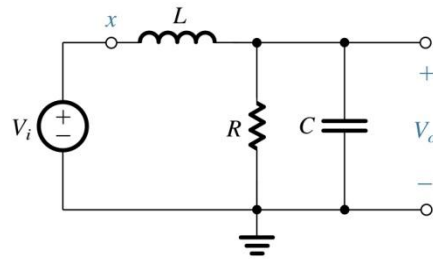
Flat gain =  $a_2$



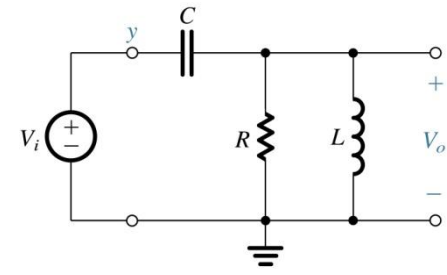
# Second-Order LCR Resonator



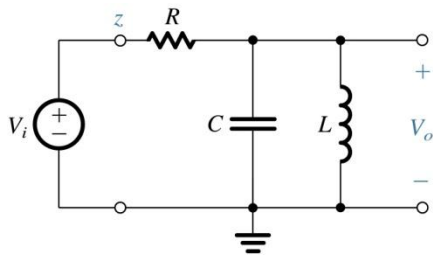
(a) General structure



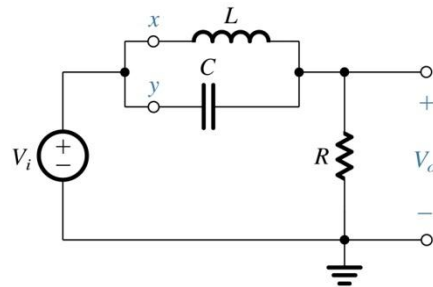
(b) LP



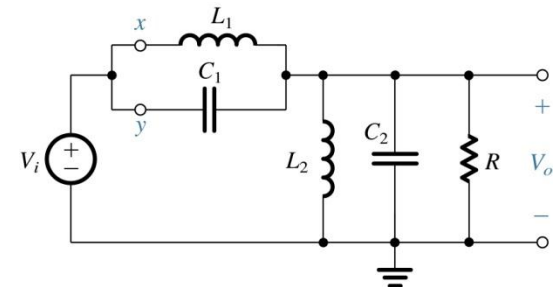
(c) HP



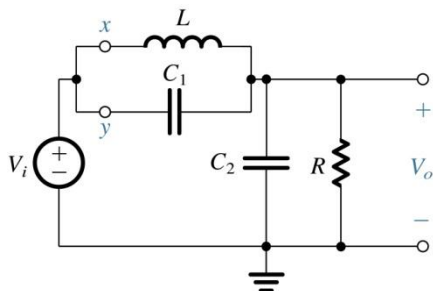
(d) BP



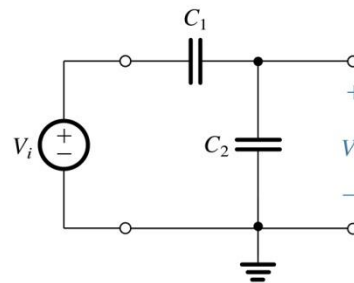
(e) Notch at  $\omega_0$



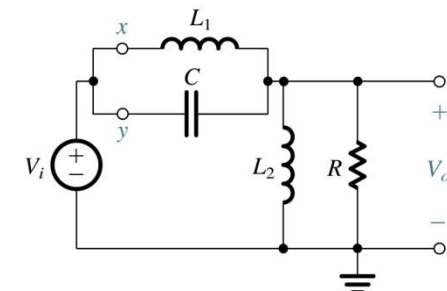
(f) General notch



(g) LPN ( $\omega_n > \omega_0$ )

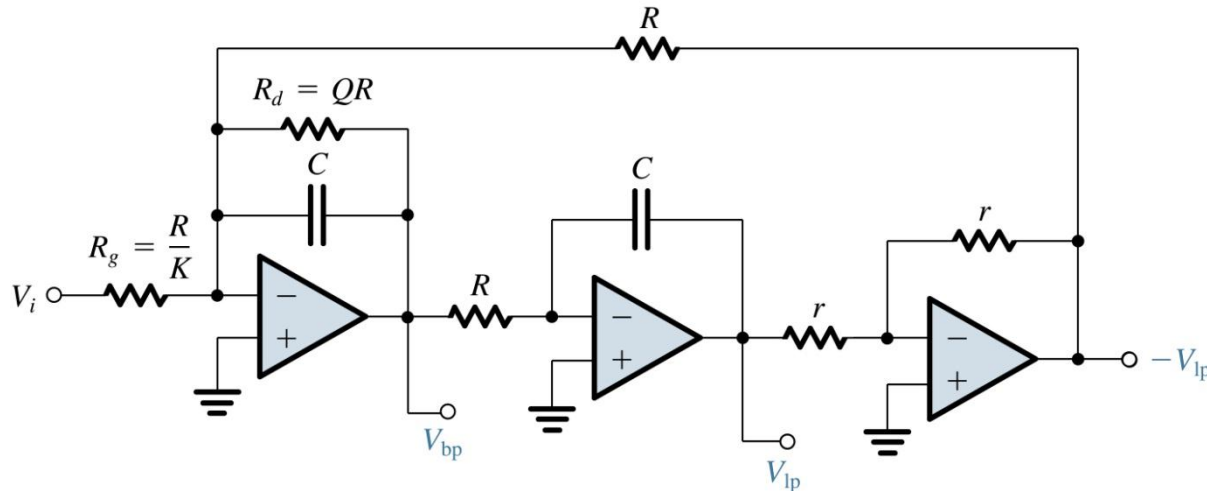
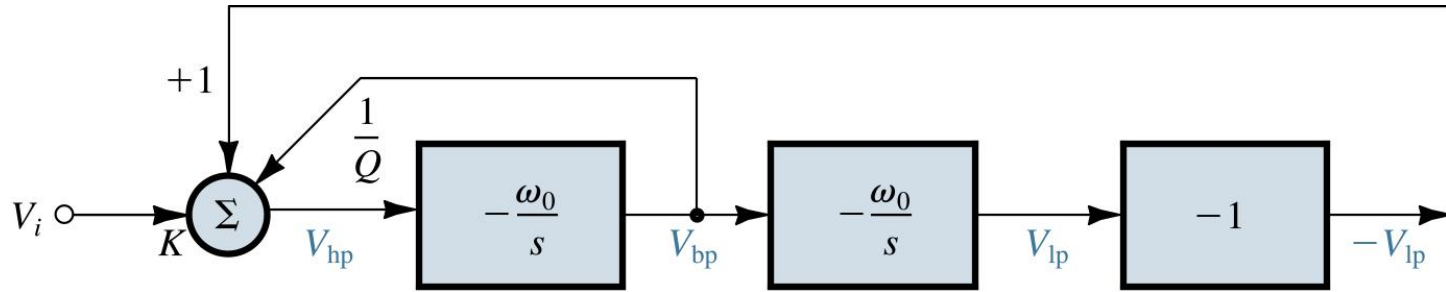


(h) LPN as  $s \rightarrow \infty$



(i) HPN ( $\omega_n < \omega_0$ )

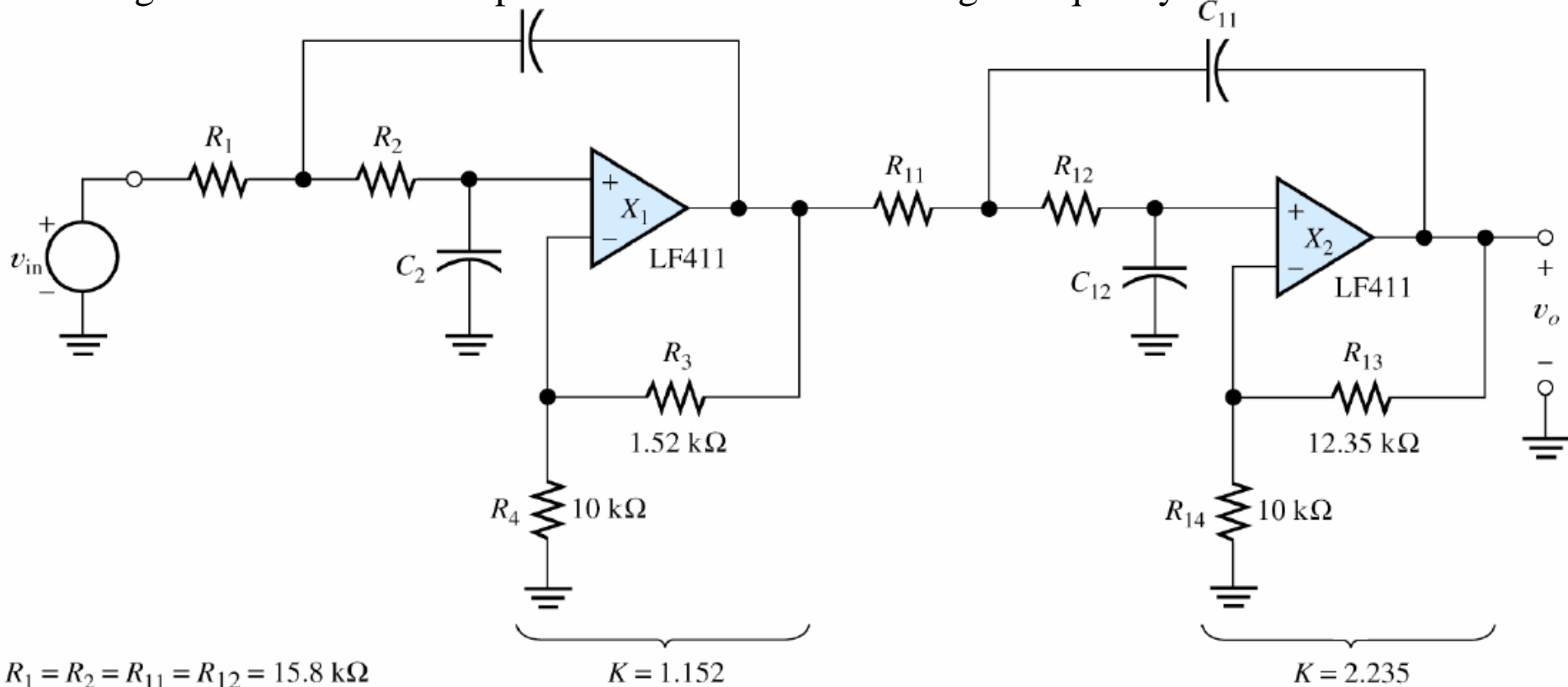
## Second-Order Active Filter: Two-Integrator-Loop



Derivation of an alternative two-integrator-loop biquad in which all op amps are used in a single-ended fashion. The resulting circuit in (b) is known as the Tow-Thomas biquad.

# Low-Pass Active Filter Design

Design a fourth-order low-pass Butterworth filter having a frequency cut-off of 100 Hz



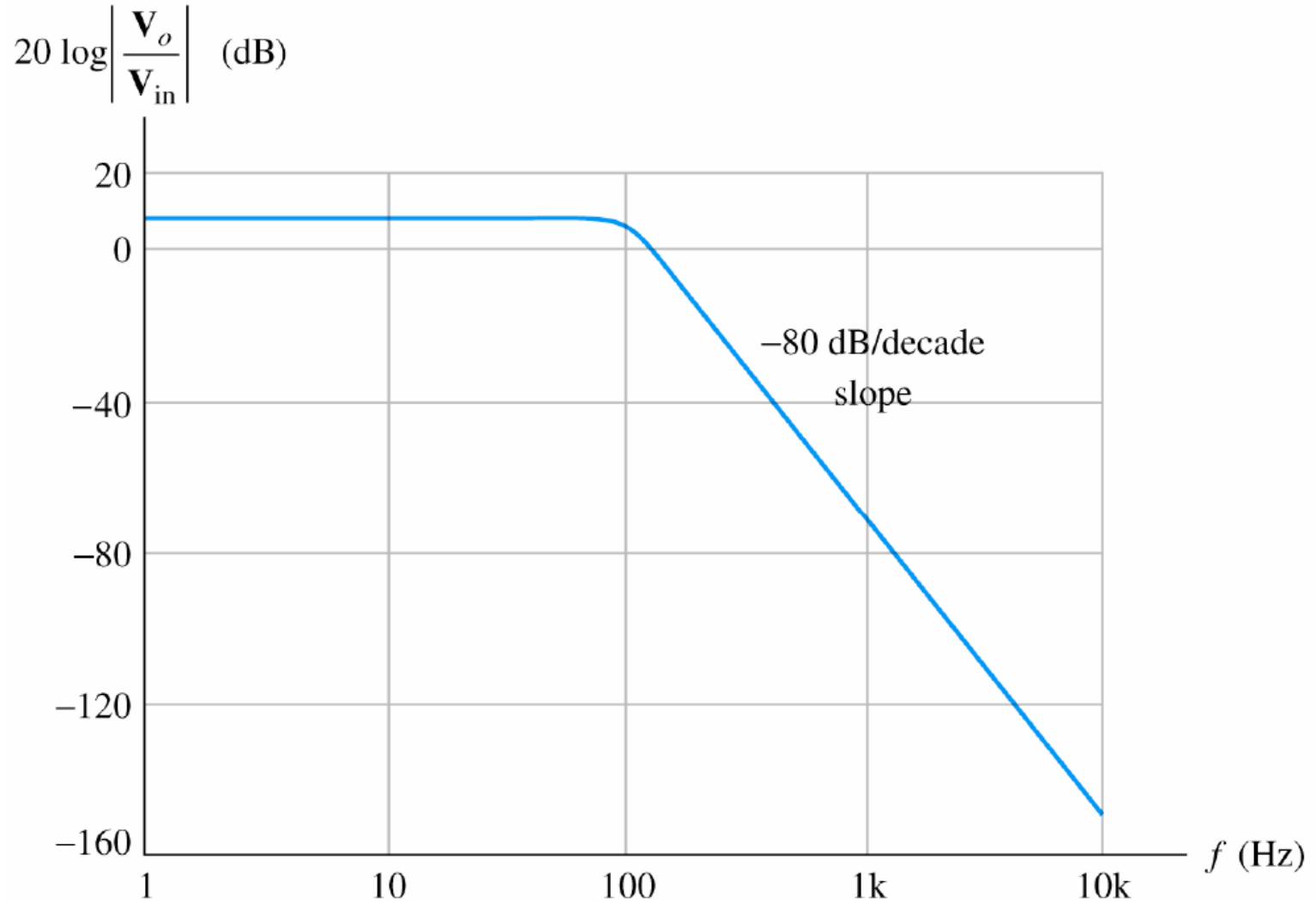
Choose  $C = 0.1 \mu\text{F}$

$$R = \frac{1}{2\pi C f_B} = \frac{1}{2\pi (0.1 \times 10^{-6})(100 \text{ Hz})}$$

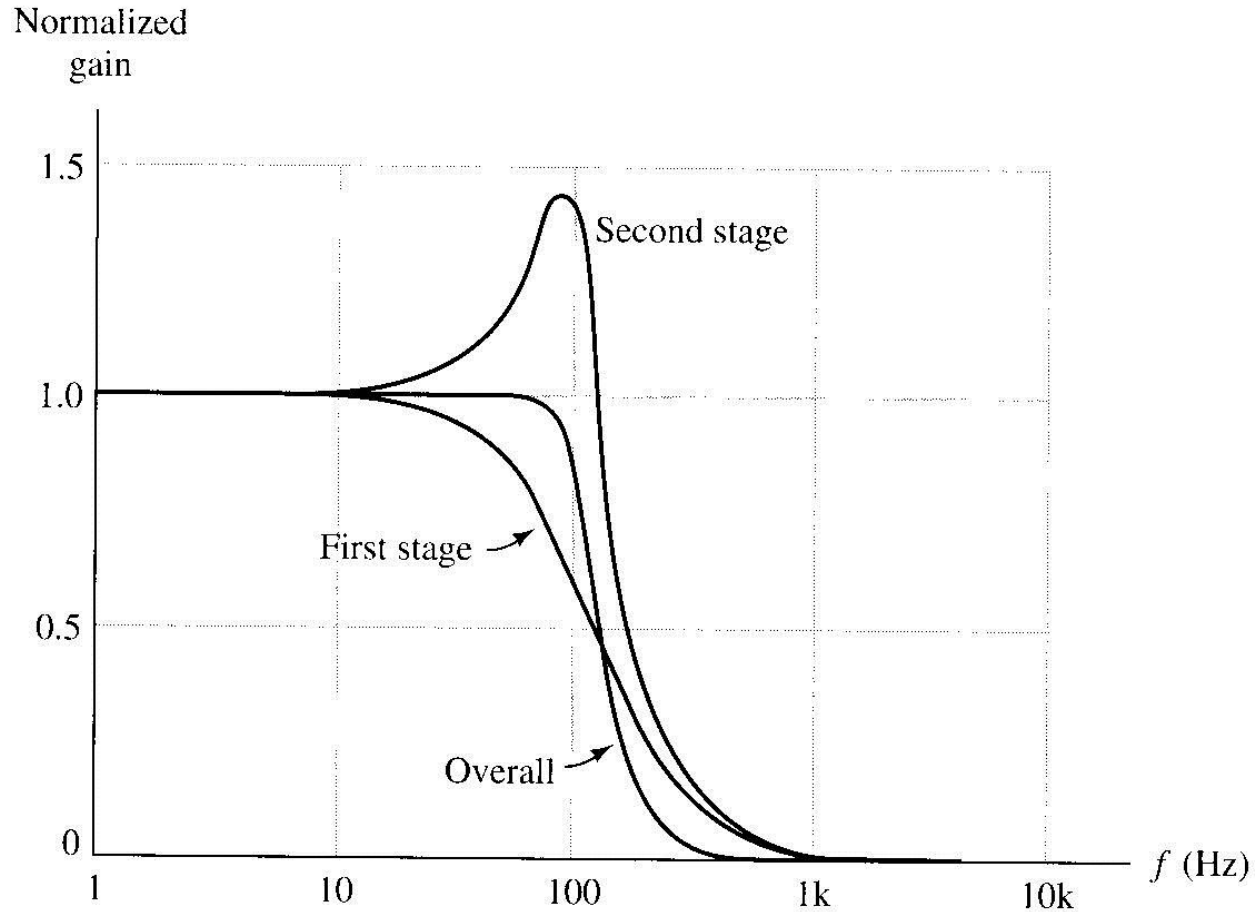
$$= 15.92 \text{ k}\Omega$$



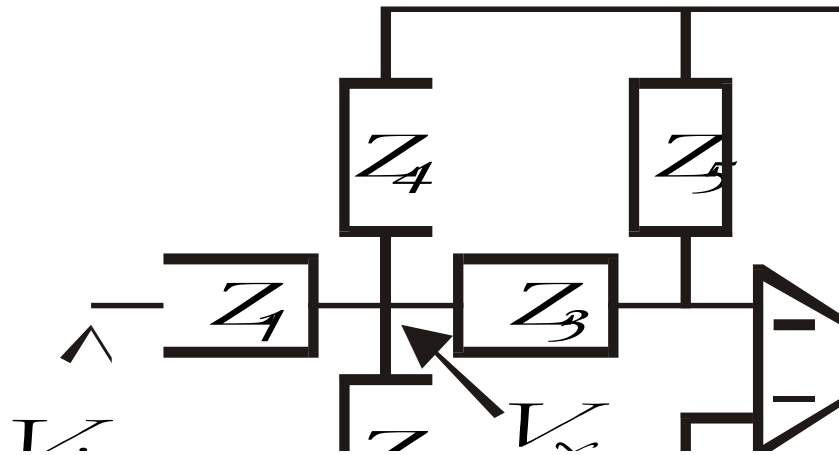
# Low-Pass Active Filter Design



# Low-Pass Active Filter Design



# Infinite-Gain Multiple-Feedback (IGMF) Negative Feedback Active Filter



$$v_i^+ = 0 \quad v_i^- = 0 \Rightarrow V_o = -\frac{Z_5}{Z_3} V_x \Rightarrow V_x = -\frac{Z_3}{Z_5} V_o \quad (1)$$

$$\text{By KCL at } V_x, \quad \frac{V_i - V_x}{Z_1} = \frac{V_x}{Z_2} + \frac{V_x}{Z_3} + \frac{V_x - V_o}{Z_4} \quad (2)$$

Substitute (1) into (2) gives

$$\frac{V_i}{Z_1} + \frac{Z_3}{Z_1 Z_5} V_o = -\frac{Z_3}{Z_5 Z_2} V_o - \frac{V_o}{Z_5} - \frac{Z_3}{Z_4 Z_5} V_o - \frac{V_o}{Z_4} \quad (3)$$

rearranging equation (3), it gives,

$$H = \frac{V_o}{V_i} = - \frac{\frac{1}{Z_1 Z_3}}{\frac{1}{Z_5} \left( \frac{1}{Z_1} + \frac{1}{Z_2} + \frac{1}{Z_3} + \frac{1}{Z_4} \right) + \frac{1}{Z_3 Z_4}}$$

Or in admittance form:

$$H = \frac{V_o}{V_i} = - \frac{Y_1 Y_3}{Y_5 (Y_1 + Y_2 + Y_3 + Y_4) + Y_3 Y_4}$$

Filter \ Value	$Z_1$	$Z_2$	$Z_3$	$Z_4$	$Z_5$
<b>LP</b>	$R_1$	$C_2$	$R_3$	$R_4$	$C_5$
<b>HP</b>	$C_1$	$R_2$	$C_3$	$C_4$	$R_5$
<b>BP</b>	$R_1$	$R_2$	$C_3$	$C_4$	$R_5$

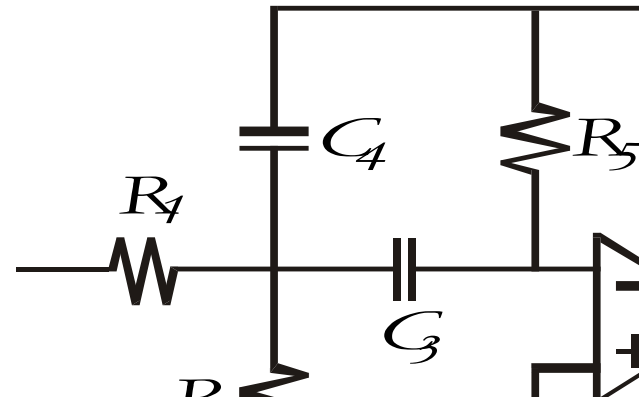
# IGMF Band-Pass Filter

Band-pass: 
$$H(s) = K \frac{s}{s^2 + as + b}$$

To obtain the band-pass response, we let

$$Z_1 = R_1 \quad Z_2 = R_2 \quad Z_3 = \frac{1}{j\omega C_3} = \frac{1}{sC_3} \quad Z_4 = \frac{1}{j\omega C_4} = \frac{1}{sC_4} \quad Z_5 = R_5$$

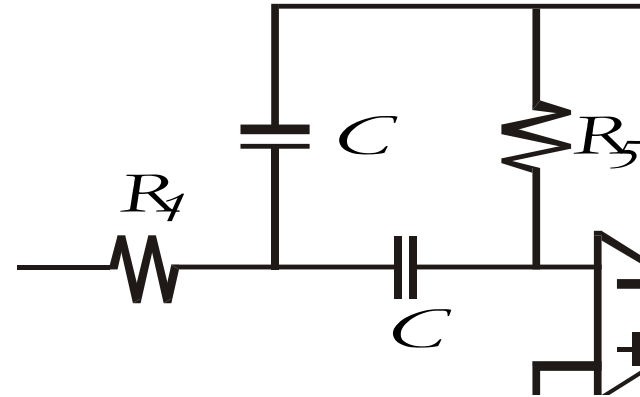
$$H(s) = - \frac{\frac{sC_3}{R_1}}{s^2 C_3 C_4 + s \frac{C_3 + C_4}{R_5} + \frac{1}{R_5} \left( \frac{1}{R_1} + \frac{1}{R_2} \right)}$$



This filter prototype has a very low sensitivity to component tolerance when compared with other prototypes.

# Simplified Design (IGMF Filter)

$$H(s) = -\frac{\frac{sC}{R_1}}{\frac{1}{R_1 R_5} + s\frac{2C}{R_5} + s^2 C^2}$$



Comparing with the band-pass response

$$H(s) = K \frac{s}{s^2 + \frac{\omega_p}{Q_p} s + \omega_p^2}$$

It gives,

$$\omega_p = \frac{1}{C\sqrt{R_1 R_5}} \quad Q_p = \frac{1}{2} \sqrt{\frac{R_5}{R_1}} \quad H(\omega_p) = -2Q^2$$

# Example: IGMF Band Pass Filter

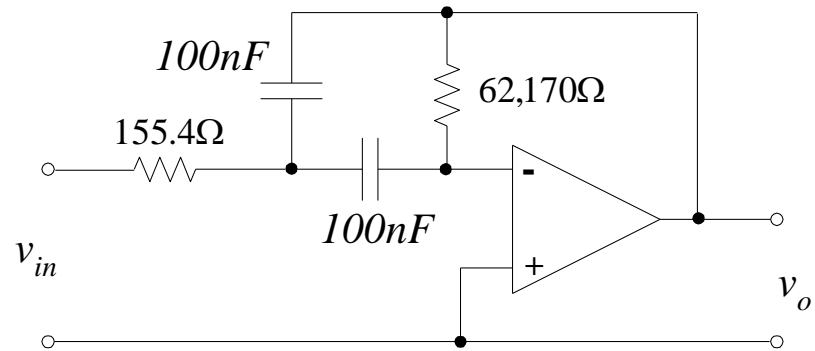
To design a band-pass filter with  $f_o = 512\text{Hz}$  and  $Q = 10$

$$\omega_p = \frac{1}{C\sqrt{R_1R_5}} = 2\pi(512\text{Hz})$$

$$C = 100\text{nF} \rightarrow R_1R_5 = 9,662,741\Omega^2$$

$$Q_p = \frac{1}{2} \frac{\sqrt{R_5}}{\sqrt{R_1}} = 10$$

$$\rightarrow R_1 = 155.4\Omega \quad R_5 = 62,170\Omega$$



With similar analysis, we can choose the following values:

$$C = 10\text{nF} \quad R_1 = 1,554\Omega \quad \text{and} \quad R_5 = 621,700\Omega$$

# Butterworth Response (Maximally Flat)

$$|H(j\omega)| = \frac{1}{\sqrt{1 + \left(\frac{\omega}{\omega_o}\right)^{2n}}}$$

where  $n$  is the order

Normalize to  $\omega_o = 1 \text{ rad/s}$

$$|\hat{H}(j\omega)| = \frac{1}{\sqrt{1 + \omega^{2n}}}$$

Butterworth polynomials:

$$|\hat{H}(j\omega)| = \frac{1}{|B_n(j\omega)|}$$

Butterworth polynomials

$$B_1(s) = s + 1$$

$$B_2(s) = s^2 + \sqrt{2}s + 1$$

$$B_3(s) = s^3 + 2s^2 + 2s + 1$$
$$= (s + 1)(s^2 + s + 1)$$

$$B_4(s) = s^4 + 2.61s^3 + 3.41s^2 + 2.61s + 1$$
$$= (s^2 + 0.77s + 1)(s^2 + 1.85s + 1)$$

$$B_5(s) = s^5 + 3.24s^4 + 5.24s^3 + 5.24s^2 + 3.24s + 1$$
$$= (s + 1)(s^2 + 0.62s + 1)(s^2 + 1.62s + 1)$$



# Second order Butterworth Filter

$$H(s) = \frac{K}{1 + sC_4(R_1 + R_2) + sR_1C_3(1 - K) + s^2R_1R_2C_3C_4} = \frac{K'}{s^2 + \frac{\omega_p}{Q_p}s + \omega_p^2}$$

$$Q_p = \frac{1}{\sqrt{\frac{R_1C_4}{R_2C_3} + \sqrt{\frac{R_2C_4}{R_1C_3} + (1 - K)\sqrt{\frac{R_1C_3}{R_2C_4}}}}$$

Setting  $R_1 = R_2$  and  $C_1 = C_2$

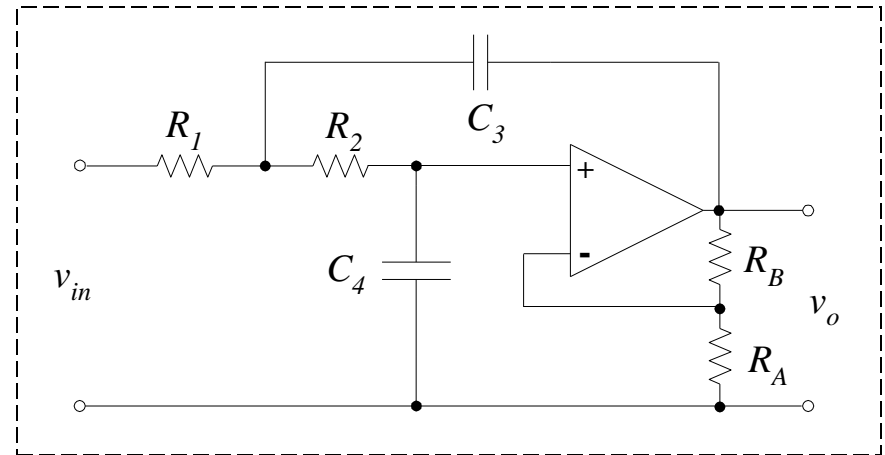
$$Q_p = \frac{1}{\sqrt{1 + \sqrt{1 + (1 - K)\sqrt{1}}}} = \frac{1}{2 + (1 - K)} = \frac{1}{3 - K}$$

Now  $K = 1 + R_B / R_A$

$$Q_p = \frac{1}{3 - K} = \frac{1}{3 - \left(1 + \frac{R_B}{R_A}\right)} = \frac{1}{2 - \frac{R_B}{R_A}}$$

For Butterworth response:

$$Q_p = \frac{1}{\sqrt{2}} \Rightarrow Q_p = \frac{1}{\sqrt{2}} = \frac{1}{2 - \frac{R_B}{R_A}}$$



We have  $2 - \frac{R_B}{R_A} = \sqrt{2} = 1.414$

We define Damping Factor (DF) as:

$$DF = \frac{1}{Q_p} = 2 - \frac{R_B}{R_A} = 1.414$$