## ELG4139 Quiz Assignment 2

## Question 1:

Propose a proper switch (MOSFET/Thyristor/GTO/IGBT) for the following applications

| An inverter for the light-rail train (LRT) locomotive operating from a DC <br> supply of 750 V . The locomotive is rated at 150 kW . The induction motor is to <br> run from standstill up to 200 Hz , with power switches frequencies up to 10 <br> kHz |  |
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| A switch-mode power supply (SMPS) for remote telecommunication <br> equipment is to be developed. The input voltage is obtained from a photovoltaic <br> array that produces a maximum output voltage of 100 V and a minimum <br> current of 200 A . The switching frequency should be higher than 100 kHz . |  |
| A HVDC transmission system transmitting power of 300 MW from one AC <br> system to another AC system both operating at 50 Hz , and the DC link voltage <br> operating at 2.0 kV . |  |
| A variable frequency drive (VFD) for a vacuum cleaner using a three phase AC <br> motor. |  |
| An ordinary compact fluorescent lamp (CFL). |  |
| An induction heater. |  |
| Battery charger up to 40 A. |  |
| An industrial motor drive of more than 1000 kW and more than 2000 kV. |  |

Question 2: Draw a block diagram for the following energy systems.

| Grid- <br> connected <br> wind energy <br> system using <br> an induction <br> generator |  |
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| Grid- <br> connected <br> Solar energy <br> System <br> (20 solar panels, <br> each with 12.5 <br> V) |  |

Question 3: Consider the following DC to DC converter. $L=24 \mu \mathrm{H}$. It is operating in DC steady-state under the following condition: $V_{\mathrm{in}}=20 \mathrm{~V}, D=0.6, P_{\mathrm{o}}=14 \mathrm{~W}$ and $f_{s}=200 \mathrm{kHz}$. Calculate the values of the generated signal forms.


Question 4: Consider a boost converter, the inductor current has $\Delta i_{\mathrm{L}}=2 \mathrm{~A}, V_{\text {in }}=5 \mathrm{~V}, V_{0}=12 \mathrm{~V}$, $P_{o}=11 \mathrm{~W}, f_{\mathrm{s}}=200 \mathrm{kHz}$. Calculate $L$ and values of the generated signal forms.


Question : Consider the following step-down and step-up chopper (two quadrant chopper). The circuit can provide both motoring forward operation ( $S_{1}$ and $D_{1}$ ) and regenerating braking operation ( $S_{2}$ and $D_{2}$ ).


For the Buck circuit ( $S_{1}$ and $D_{1}$ ), determine the duty cycle and turn-on time in the motoring mode if $n=500 \mathrm{r} / \mathrm{min}$, and $i_{0}=90 \mathrm{~A}$. Assume $V_{\mathrm{s}}=120 \mathrm{~V}, E_{\mathrm{a}}=0.1 \mathrm{n}, R_{\mathrm{a}}=0.2 \mathrm{Ohm}, f_{\mathrm{s}}=300 \mathrm{~Hz}$.

Calculate the absorbed power in the motor armature winding and the power delivered by the voltage supply. What is the role of the diode $\left(D_{1}\right)$ ? Draw the Buck (step-down chopper) voltage waveform first with $D_{1}$ and second without $D_{1}$.

For the Boost ( $S_{2}$ and $D_{2}$ ) circuit, determine the duty cycle and turn-on time in the motoring mode if $n=380 \mathrm{I} / \mathrm{min}$, and $i_{\mathrm{o}}=-90 \mathrm{~A}$. Assume $V_{\mathrm{s}}=120 \mathrm{~V}, E_{\mathrm{a}}=0.1 \mathrm{n}, R_{\mathrm{a}}=0.2 \mathrm{Ohm}, f_{5}=300$ Hz . Calculate the absorbed power in the motor armature winding and the power delivered by the voltage supply. Also draw the output voltage waveform.

Question : An IGBT- based one-quadrant chopper is used to power a DC motor. The motor armature winding $R_{\mathrm{a}}=0.25 \mathrm{Ohm}$ and winding inductance $L_{\mathrm{a}}=1 \mathrm{mH}$. The input DC voltage $V_{\mathrm{d}}=$ 250 V . The armature constant of the DC motor is $K_{2} \varphi=0.98 \mathrm{~V} / \mathrm{rad} / \mathrm{sec}$. When the duty cycle is 0.5 , the motor is running at 1200 rpm . The switching frequency $f_{5}=1 \mathrm{kHz}$. Determine the operation mode of the converter and the ripple torque $\Delta \mathrm{T}$. Hint: The converter usually operates at two modes: discontinuous conduction mode (DCM) and continuous conduction mode (CCM). DCM occurs because switching ripple in inductor current or capacitor voltage causes polarity of applied switch current or voltage to reverse ( 2 marks).


Use: $E_{\mathrm{a}}=K_{\mathrm{a}} \varphi \omega ; \Delta \mathrm{T}=K_{\mathrm{a}} \varphi \Delta I ; I_{\min }=\frac{V_{d}}{R_{a}} \frac{e^{\operatorname{ton} / \tau}-1}{e^{t s / \tau}-1}-\frac{E_{a}}{R_{a}} ; I_{\max }=\frac{V_{d}-E_{a}}{R_{a}}\left(1-e^{\operatorname{ton} / \tau}\right)$

